# **Series 19 SMART Modulating Electric Actuator User Manual**





#### **Description**

The Series 19 smart modulating electric actuator features a reversing motor with multivoltage capabilities, 95 VAC to 265 VAC (50/60 Hz) or 24 VAC/VDC, an OLED screen, an internal heater, positioner, transmitter, alarm/fault contacts, a NEMA Type 4X enclosure, manual override, visual beacon position indication, LED fault indicator (blue), ISO mounting, and flying leads. The alarm/fault contacts are SPST and rated for 0.1 Amp @ 250 VAC/0.5 Amp @ 30 VDC, and are factory calibrated.

### Cover removal is NOT required for installation and will void warranty!!

Additional options are NOT available for this model.

Electrical Requirement
WARNING: Do not open actuator cover as warranty will be void!!

Model Number	Torque	95 VAC to 265 VAC		24 VAC/24 VDC		Cycle Time per 90	Weight	
Model Number	(in-lbs)	Amp Draw	Duty Cycle	Amp Draw	Duty Cycle	Degrees (Seconds)	(Pounds)	
S20HC1C3W	177	0.34	75%	0.78	75%	10 seconds	1.7	
S50HC1C3W	442	0.39	75%	0.84	75%	10 seconds	3.5	
S110HC1C3W	973	1.24	75%	2.89	75%	10 seconds	4.8	
S400HM2W	3540	1.83	75%	4.80	75%	25 seconds	13.23	

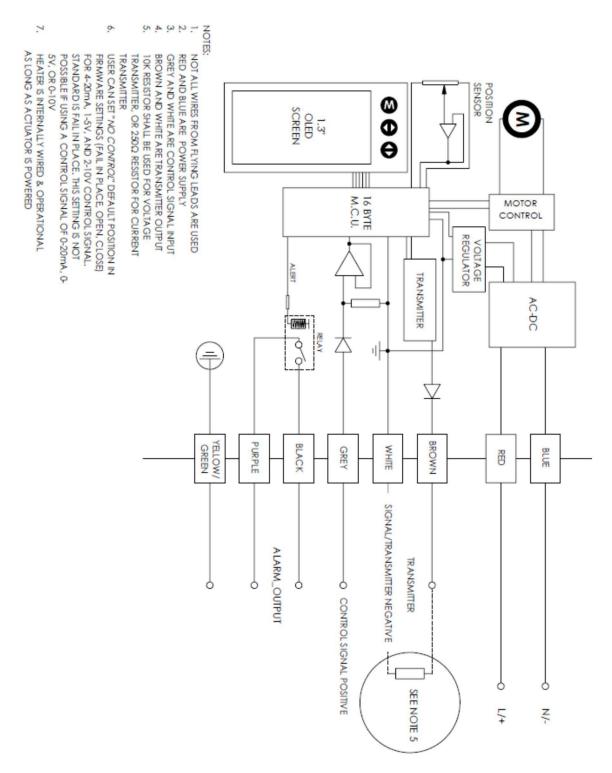
NOTE: Amp rating is considered running. Duty cycles are for ambient temperature (73° F)

The Series 19 electric actuator has a sealed cable gland with 2 meter flying leads. The electrician is required to make field connections as per the wiring schematic shown in this manual for model numbers and voltages listed above. The electrician is responsible for following all and any, local and/or agency wiring practices.

**Note**: Not all wires provided will be used.

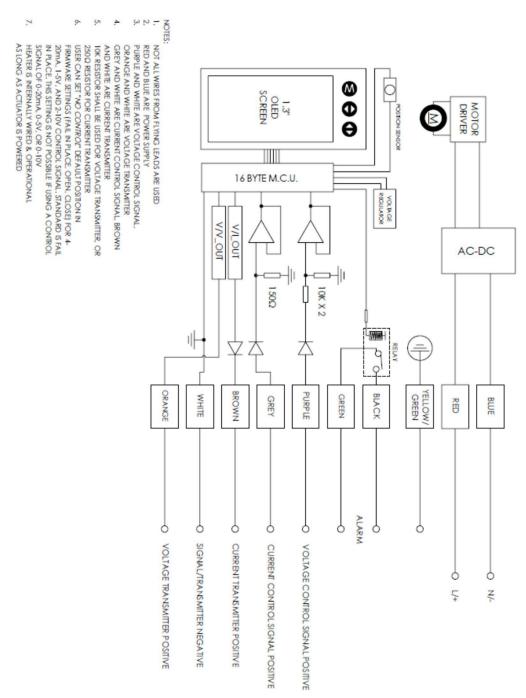
Heater is internally wired and operational as long as actuator is powered.

Size 20 ONLY
Size 20 is specific to accept only voltage or current as a control signal/loop



Size 20 will be labelled specifically as a voltage or current control signal/loop, and cannot be changed via onboard firmware. If a different control signal/loop is required, then another unit with the specific control signal/loop must be used.

Size 50 – 400
Size 50 – 400 can be calibrated for EITHER a voltage or a current control signal/loop via onboard firmware. Please contact the factory for instructions.



#### **Manual Override Operation**

Remove manual override hex key from storage position located on the bottom of actuator, which is secured by stainless clips. To operate the manual override, insert hex key into hex socket located on top of actuator and rotate to manually cycle valve (CCW

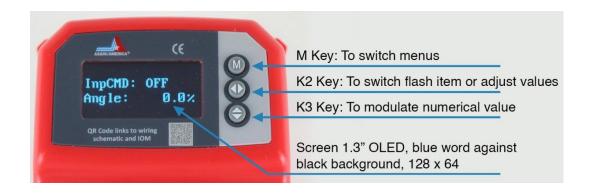
to open, CW to close). When finished using the manual override, it is imperative to remove the hex key and place it back into storage on actuator base, making sure that it "clicks" into the locking position.

<u>CAUTION:</u> The manual override should only be used when there is no power applied to actuator. When power is restored, the actuator will automatically resume normal operation.

#### **Local Controls Operation**

The actuator can be locally controlled and driven to the open or closed position via OLED screen and push buttons. This simple procedure is detailed below.

Press and hold the " $\updownarrow$ " button for 3 seconds. "K3" will flash in the top right hand corner and the unit will ask for a password. At this time, the password of "111" can be entered with " $\updownarrow$ " selecting numbers and " $\leftrightarrow$ " selecting the field. Once password is entered, press the "M" button to enter manual mode. The actuator can now be opened and closed via the push buttons. Press the " $\updownarrow$ " button to OPEN the actuator. Press the " $\leftrightarrow$ " button to CLOSE the actuator. To exit manual mode, press the M button or wait approximately 120 seconds and the manual mode will time out and exit. The actuator will not respond to control signals from the PLC until taken out of manual mode.



# **Troubleshooting**

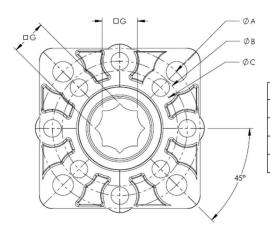
Actuator does not respond

Power not connected	Connect power
Voltage below level or incorrect	Confirm correct voltage
Torque limiter tripped	Power unit in opposite direction, then power to original position to confirm a tripped torque limiter
Loose/poor termination	Confirm proper termination
Incorrect signal provided to actuator	Verify that control signal from PLC matches control signal of actuator. *Size 20 is provided as ONLY accepting a mA signal or ONLY accepting a current control signal

## Crossed signal wiring

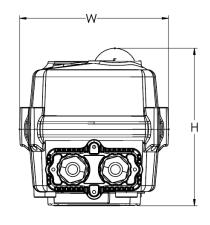
Confirm that control signal wiring is terminated at the appropriate wiring location of actuator (0-10 VDC signal connected to 4-20 mA actuator wiring, as an example)

### Series 19 ISO 5211 Output

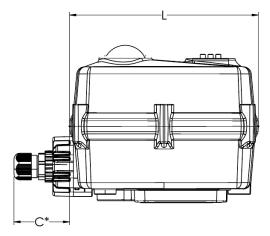


Size	Α	В	С	G
S20	F05 (M6)	FO4 (M5)	F03 (M5)	14MM
S50	F07 (M8)	F05 (M6)	N/A	14MM
S110	F07 (M8)	F05 (M6)	N/A	17MM
S400	F10 (M10)	F07 (M8)	N/A	22MM

### **Series 19 Envelope Dimensions**



Size	L	w	Н	С
S20	4.01	2.76	3.54	N/A
S50	5.13	4.33	4.72	N/A
S110	5.75	4.53	4.80	1.69
S400	8.78	6.28	6.72	1.72



\*DIMENSION C IS ONLY FOR \$110 AND \$400